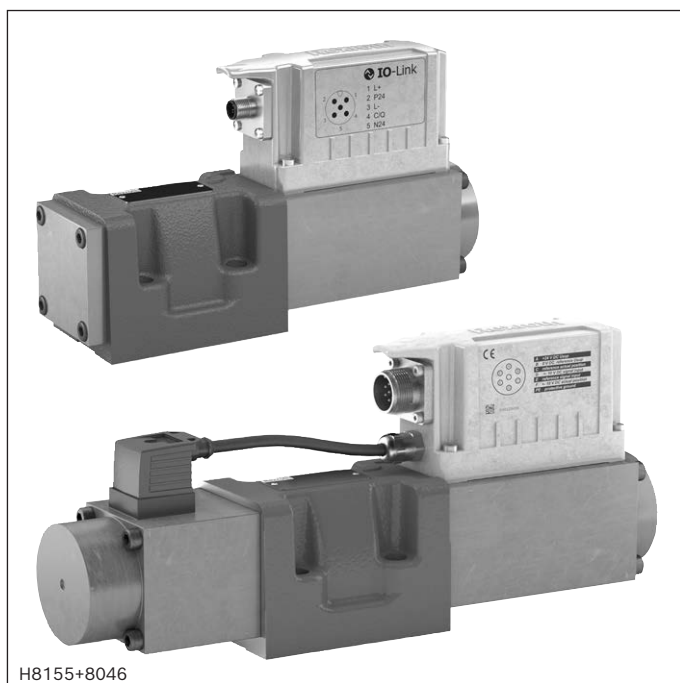


Directional control valves, direct operated, with electrical position feedback and integrated electronics (OBE)

Type 4WRPE



H8155+8046

- ▶ Size 10
- ▶ Component series 3X
- ▶ Maximum operating pressure 350 bar
- ▶ Rated flow 50, 80 l/min
- ▶ Digital interface, IO link for I4.0



Features

- ▶ Reliable – proven and robust design
- ▶ Energy-efficient – no pilot oil demand, high flows with low pressure differential
- ▶ Flexible – suitable for position and velocity control
- ▶ Precise – high response sensitivity and little hysteresis
- ▶ Safe – shut-off of the second solenoid by means of ISA adapter possible
- ▶ IO-Link interface, optional. Use of the valve with IO-Link as a shut-off element up to category 3, PL d according to EN 13849-1.

Contents

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Ordering code	2
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Ordering code

01	02	03	04	05	06	07	08	09	10	11	12	13	14	15	
4	WRP	E	10			S	J	-	3X	/		/		24	*

01	4 main ports	4
02	Directional control valve, direct operated	WRP
03	With integrated electronics	E
04	Size 10	10
05	Symbols; possible version see page 3	

Nominal flow (Δp = 5 bar per control edge)

06	50 l/min (only symbols E, E1-, V and W6-)	50
	80 l/min	80

Flow characteristic

07	Progressive	S
08	Overlap jump (opening point 5 command value with symbols E, E1-, EA, W6- and W8-)	J
09	Component series 30 ... 39 (30 ... 39: unchanged installation and connection dimensions)	3X

Seal material (observe compatibility of seals with hydraulic fluid used, see page 9)

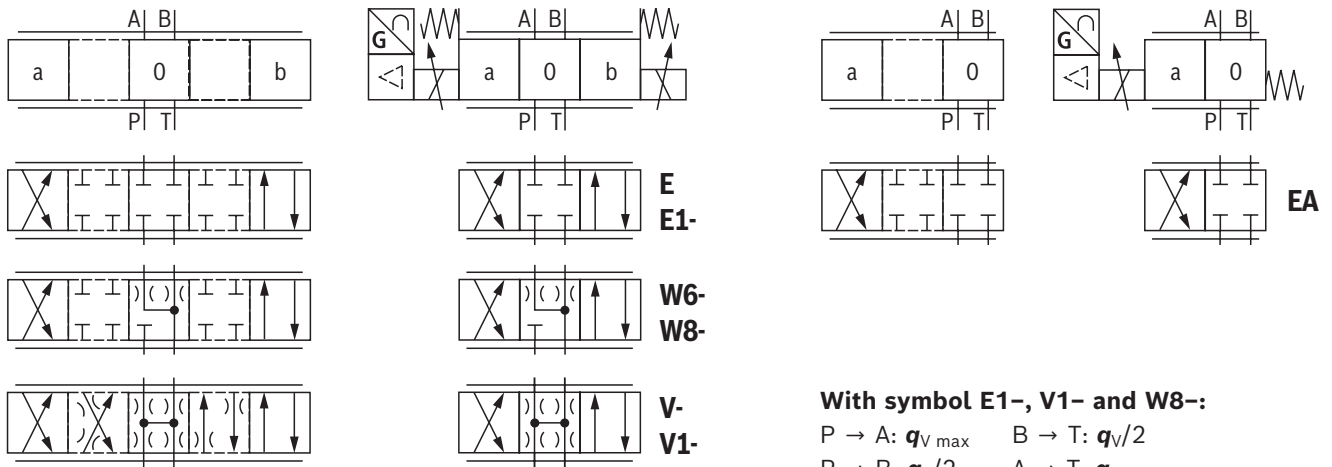
10	NBR seals	M ♦
	FKM seals	V
11	Without damping plate	no code
	With damping plate	D
12	Supply voltage 24 V	24

Interfaces of the control electronics

13	Command value input ± 10 V	A1 ♦
	Command value input 4 ... 20 mA	F1 ♦
	IO-Link interface	L1 ♦
	Command value ± 10 mA, actual value 4 ... 20 mA, release (connector 6+PE)	C6
14	Without electronics protection membrane	no code ♦
	With electronics protection membrane	-967
15	Further details in the plain text	

 **Notice:** ♦ = Preferred type

Symbols



Notice:

Representation according to DIN ISO 1219-1.
Hydraulic interim positions are shown by dashes.

Function, section (4/3 directional valve)

The valve type 4WRPE is a direct operated directional control valve with electric position feedback and integrated electronics (OBE).

Set-up

The valve basically consists of:

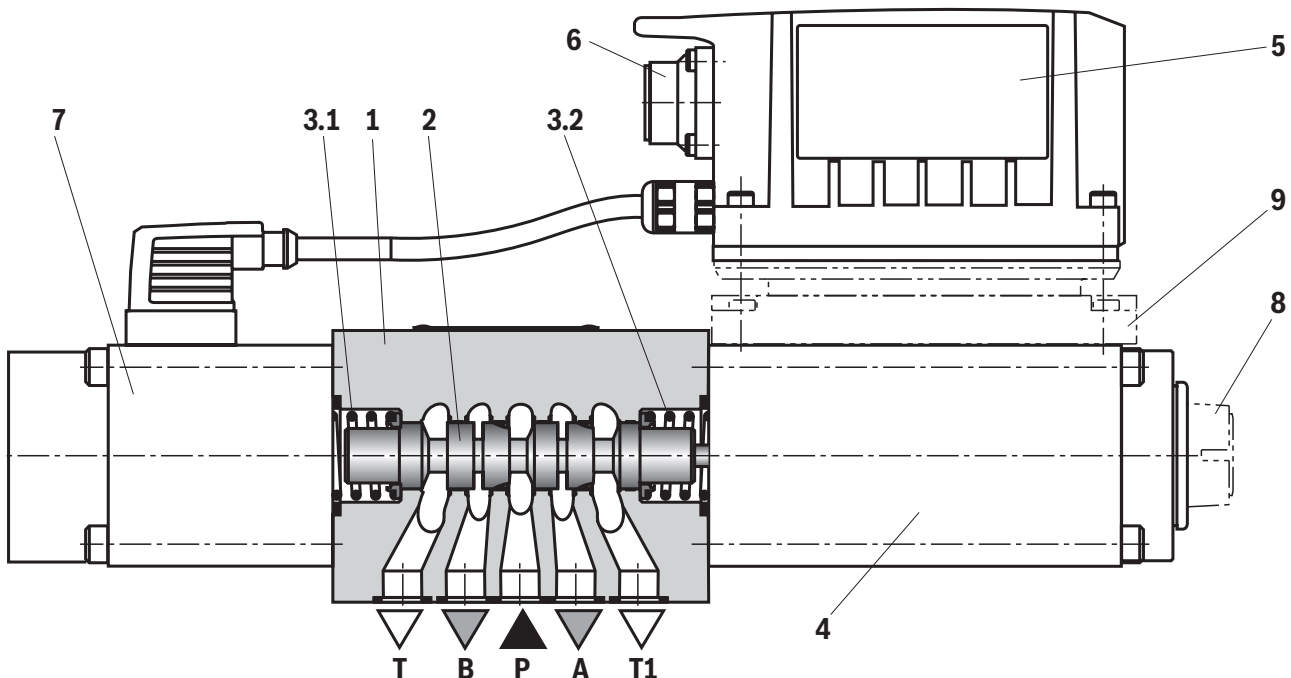
- ▶ Valve housing (1)
- ▶ Control spool (2) with compression springs (3.1 and 3.2)
- ▶ Control solenoid with position transducer (4) (optional with electronics protection membrane (8))
- ▶ Stroke solenoid (7)
- ▶ On-board electronics (OBE) (5) with analog (6) or IO-Link interface (optionally with damping plate (9))

Function

The integrated electronics (OBE) compares the specified command value to the position actual value. In case of control deviations, the relevant solenoid will be activated. Due to the changed magnetic force, the control spool (2) is adjusted against the corresponding spring. Stroke/control spool cross-section is controlled proportionally to the command value. In case of a command value presetting of 0 V, the electronics adjust the control spool (2) to central position.

Safety function (IO-Link shut-off)

By shutting off the supply voltage at the IO-Link master (Class B-Port), pin 2 and 5, the IO-Link valve can be safely switched off. After shut-off of the supply voltage, the control spool of the valve is set to spring-centered central position. In order to also guarantee the hydraulic prerequisite for the safety shut-down, the overlap of control spool must also be considered. Sufficient overlap is guaranteed by the symbols E, E1-, W6- and W8- (MTTF_D values see data sheet 08012). Depending on the category or application, additional safety measures must be taken according to EN 13849-1 and operating instructions 29118-B must be observed. The safe shut-off is not part of the IO-Link valve and must be taken into account for the safe design of the machinery.



Function, section (4/3 directional valve)

Error detection

In the following cases of error, the electronics will de-energize the control solenoids:

- ▶ Falling below the minimum supply voltage $\leq 15\text{ V}$ (restarting $\geq 17.5\text{ V}$).
- ▶ Only at interface "F1":
 - Falling below the minimum current command value of 2 mA (includes cable break of the command value line (current loop)).
- ▶ Only at interface "L1":
 - Enable inactive, communication interruption (watchdog)
 - In case of internal IO-Link error
- ▶ Only at interface "C6":
 - Additionally, release inactive

The control spool (2) is kept in the mechanical central position by the compression springs (3.1 and 3.2) (with symbol V, this does not correspond to the hydraulic central position).

Damping plate "D"

The damping plate (9) reduces the acceleration amplitudes on the on-board electronics (frequencies $>300\text{ Hz}$).



Notice:

Using the damping plate is not recommended for applications with mainly low-frequency excitation $<300\text{ Hz}$.

Electronics protection membrane "-967"

To prevent condensate formation in the housing of the integrated electronics (OBE), an electronics protection membrane (8) can be used.

Recommended for use outside industry-standard conditions with high ambient air humidity and significant cyclic temperature changes (e.g. outdoors).



Notice:

- ▶ 4/3 directional control valves do not have a leakage-free basic locking when deactivated. Leakage must be considered when designing the drive.
- ▶ When using the valve with IO-Link interface in compliance with category 3 according to EN 13849-1, adequate cyclic diagnosis or monitoring of the valve function outside of the valve by the control system must be implemented by the machine integrator. Without suitable diagnostic measures, only cat. B or 1 according to EN 13849-1.

Function, section (4/2 directional valve)

The valve type 4WRPE is a direct operated directional control valve with electric position feedback and integrated electronics (OBE).

Set-up

The valve basically consists of:

- ▶ Valve housing (1)
- ▶ Control spool (2) with compression springs (3)
- ▶ Control solenoid with position transducer (4) (optional with electronics protection membrane (8))
- ▶ On-board electronics (OBE) (5) with analog (6) or IO-Link interface (optionally with damping plate (9))

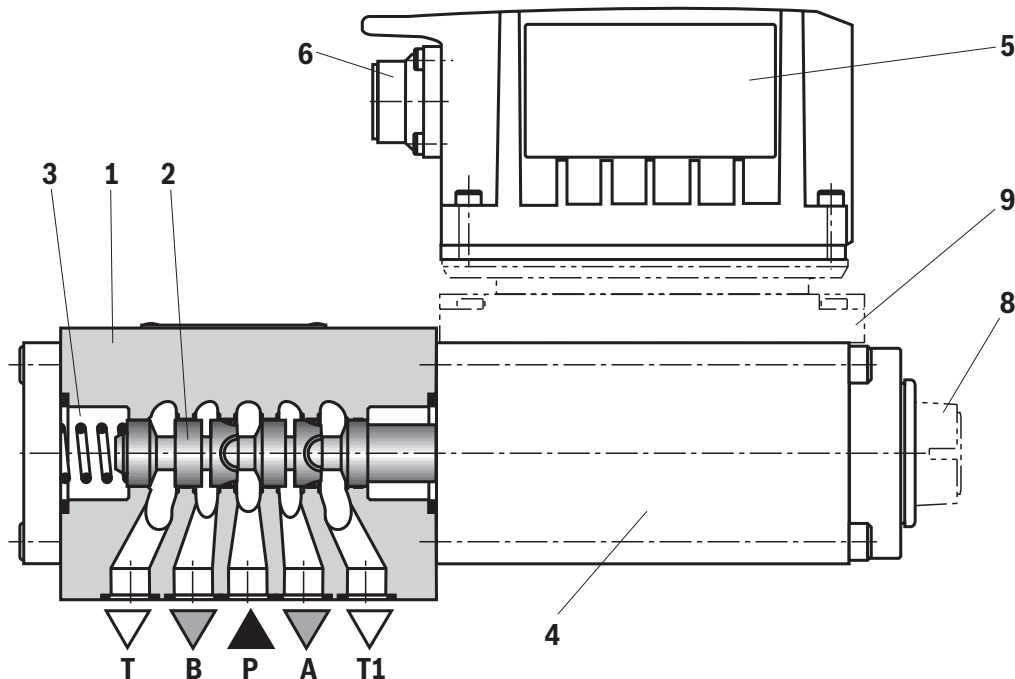
Function

The integrated electronics (OBE) compares the specified command value to the position actual value. In case of control deviations, the control solenoid will be activated. Due to the changed magnetic force, the control spool (2) is adjusted against the control spring. Stroke/control spool cross-section is controlled proportionally to the command value. With a positive command value presetting, the valve opens from P to B or A to T. Negative command values lead to no change in the control spool position.

Safety function (IO-Link shut-off)

By shutting off the supply voltage at the IO-Link master (Class B-Port), pins 2 and 5, the IO-Link valve can be safely switched off. After shut-off of the supply voltage, the control spool of the valve is set to spring-centered central position. In order to also guarantee the hydraulic prerequisite for the safety shut-down, the overlap of control spool must also be considered. Sufficient overlap is guaranteed by the symbol EA (MTTF_D values see data sheet 08012).

Depending on the category or application, additional safety measures must be taken according to EN 13849-1 and operating instructions 29118-B must be observed. The safe shut-off is not part of the IO-Link valve and must be taken into account for the safe design of the machinery.



Function, section (4/2 directional valve)

Error detection

In the following cases of error, the electronics will de-energize the control solenoid:

- ▶ Falling below the minimum supply voltage $\leq 15 \text{ V}$ (restarting $\geq 17.5 \text{ V}$).
- ▶ Only at interface "F1":
 - Falling below the minimum current command value of 2 mA (includes cable break of the command value line (current loop)).
- ▶ Only at interface "L1":
 - Enable inactive, communication interruption (watchdog)
 - In case of internal IO-Link error
- ▶ Only at interface "C6":
 - Additionally, release inactive

Damping plate "D"

The damping plate (9) reduces the acceleration amplitudes on the on-board electronics (frequencies $>300 \text{ Hz}$).



Notice:

Using the damping plate is not recommended for applications with mainly low-frequency excitation $<300 \text{ Hz}$.

Electronics protection membrane "-967"

To prevent condensate formation in the housing of the integrated electronics (OBE), an electronics protection membrane (8) can be used.

Recommended for use outside industry-standard conditions with high ambient air humidity and significant cyclic temperature changes (e.g. outdoors).



Notice:

- ▶ 4/2 directional control valves do not have a leakage-free basic locking when deactivated. Leakage must be considered when designing the drive.
- ▶ When using the valve with IO-Link interface in compliance with category 3 according to EN 13849-1, adequate cyclic diagnosis or monitoring of the valve function outside of the valve by the control system must be implemented by the machine integrator. Without suitable diagnostic measures, only cat. B or 1 according to EN 13849-1.

Technical data

(For applications outside these values, please consult us!)

General			
Type of connection		Subplate mounting	
Porting pattern		ISO 4401-05-04-0-05	
Weight	► 4/3-way version	kg	7.6
	► 4/2-way version	kg	6.0
Installation position		Any	
Ambient temperature range		°C	−20 ... +60
Storage temperature range with UV protection		°C	+10 ... +40
Transport temperature		°C	−30 ... +80
Maximum storage time		Years	1 (if the storage conditions are observed, refer to the operating instructions 07600-B)
Maximum relative humidity (no condensation)		%	95
Protection class according to EN 60529		IP65 (if suitable and correctly mounted mating connectors are used)	
Maximum surface temperature		°C	150
MTTF _D value according to EN ISO 13849		Years	150 (for further details see data sheet 08012)
Sine test according to DIN EN 60068-2-6	► Without damping plate	10 ... 2000 Hz / maximum of 10 g / 10 cycles / 3 axes	
	► With damping plate ¹⁾	10 ... 2000 Hz / maximum of 10 g / 10 cycles / 3 axes	
Noise test according to DIN EN 60068-2-64	► Without damping plate	20 ... 2000 Hz / 10 g _{RMS} / 30 g peak / 30 min. / 3 axes	
	► With damping plate ¹⁾	20 ... 2000 Hz / 10 g _{RMS} / 30 g peak / 24 h / 3 axes	
Transport shock according to DIN EN 60068-2-27	► Without damping plate	15 g / 11 ms / 3 shocks / 3 axes	
	► With damping plate ¹⁾	15 g / 11 ms / 3 shocks / 3 axes	
Shock according to DIN EN 60068-2-27	► With damping plate ¹⁾	35 g / 6 ms / 1000 shocks / 3 axes	
Conformity	► CE according to EMC directive 2014/30/EU, tested according to	EN 61000-6-2 and EN 61000-6-3	
	► RoHS directive	2011/65/EU ²⁾	

Hydraulic			
Maximum operating pressure	► Ports A, B, P	bar	350
	► Port T	bar	200
Hydraulic fluid		See table on page 9	
Viscosity range	► Recommended	mm ² /s	20 ... 100
	► Maximum admissible	mm ² /s	10 ... 800
Hydraulic fluid temperature range (flown-through)		°C	−20 ... +70
Maximum admissible degree of contamination of the hydraulic fluid; cleanliness class according to ISO 4406 (c)		Class 18/16/13 ³⁾	
Rated flow at $\Delta p = 5$ bar per control edge ⁴⁾		l/min	50; 80

¹⁾ Not recommended for applications with mainly low-frequency excitation <300 Hz

²⁾ The product fulfills the substance requirements of the RoHS directive 2011/65/EU.

³⁾ The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the life cycle of the components.

⁴⁾ Flow for deviating Δp (per control edge):

$$q_x = q_{Vnom} \cdot \sqrt{\frac{\Delta p_x}{5}}$$

**Notice:**

The specified technical data were measured with HLP46 and $\vartheta_{oil} = 40 \pm 5$ °C.

Technical data

(For applications outside these values, please consult us!)

Hydraulic fluid	Classification	Suitable sealing materials	Standards
Mineral oils	HL, HLP, HLPD, HVLP, HVLDP	NBR, FKM	DIN 51524
Bio-degradable	► Insoluble in water	HETG	ISO 15380
		HEES	
	► Soluble in water	HEPG	ISO 15380
Flame-resistant	► Water-free	HFDU (glycol base)	ISO 12922
		HFDU (ester base)	
		HFDR	
	► Containing water	HFC (Fuchs: Hydrotherm 46M, Fuchs Renosafe 500; Petrofer: Ultra Safe 620; Houghton: Safe 620; Union: Carbide HP5046)	ISO 12922



Important information on hydraulic fluids:

- For further information and data on the use of other hydraulic fluids, please refer to the data sheets above or contact us.
- There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.).
- The ignition temperature of the hydraulic fluid used must be 50 K higher than the maximum surface temperature.
- Bio-degradable and flame-resistant – containing water:
 - If components with galvanic zinc coating (e.g. version "J3" or "J5") or parts containing zinc are used, small amounts of dissolved zinc may get into the hydraulic system and cause accelerated aging of the hydraulic fluid. Zinc soap may form as a chemical reaction product, which may clog filters, nozzles and solenoid valves – particularly in connection with local heat input.
- Flame-resistant – containing water:
 - Due to the increased cavitation tendency with HFC hydraulic fluids, the life cycle of the component may be reduced by up to 30% as compared to the use with mineral oil HLP. In order to reduce the cavitation effect, it is recommended – if possible specific to the installation – backing up the return flow pressure in ports T to approx. 20% of the pressure differential at the component.
 - Dependent on the hydraulic fluid used, the maximum ambient and hydraulic fluid temperature must not exceed 50 °C. In order to reduce the heat input into the component, the command value profile is to be adjusted for proportional and high-response valves.

Static/dynamic		
Hysteresis	%	<0.25
Range of inversion	%	<0.05
Response sensitivity	%	<0.05
Manufacturing tolerance q_{Vmax}	%	<10
Temperature drift (temperature range 20 °C ... 80 °C)		Zero shift <0.2
Pressure drift	%/100 bar	Zero shift <0.2
Zero point calibration	%	±1 (ex works)

Technical data

(For applications outside these values, please consult us!)

Electrical, integrated electronics (OBE) – Interface "A1"			
Supply voltage	► Nominal value	VDC	24
	► Minimum	VDC	19
	► Maximum	VDC	36
	► Maximum residual ripple	Vpp	2.5
	► Maximum power consumption	VA	40
	► Fuse protection, external	A _T	2.5 (time-lag)
Relative duty cycle time according to VDE 0580		%	S1 (continuous operation)
Functional ground and screening		See pin assignment on page 14 (CE-compliant installation)	
Maximum voltage of the differential inputs against 0 V		D → B; E → B (max. 18 V)	
Command value (differential amplifier)	► Measurement range	V	±10
	► Input resistance	kΩ	>100
Actual value (test signal)	► Output range	V	±10
	► Minimum load impedance	kΩ	>1

Electrical, integrated electronics (OBE) – Interface "F1"			
Supply voltage	► Nominal value	VDC	24
	► Minimum	VDC	19
	► Maximum	VDC	36
	► Maximum residual ripple	Vpp	2.5
	► Maximum power consumption	VA	40
	► Fuse protection, external	A _T	2.5 (time-lag)
Relative duty cycle time according to VDE 0580		%	S1 (continuous operation)
Functional ground and screening		See pin assignment on page 14 (CE-compliant installation)	
Maximum voltage of the differential inputs against 0 V		D → B; E → B (max. 18 V)	
Command value	► Input current range	mA	4 ... 20
	► Input resistance	kΩ	200
Actual value (test signal)	► Output range	mA	4 ... 20
	► Maximum load	Ω	500

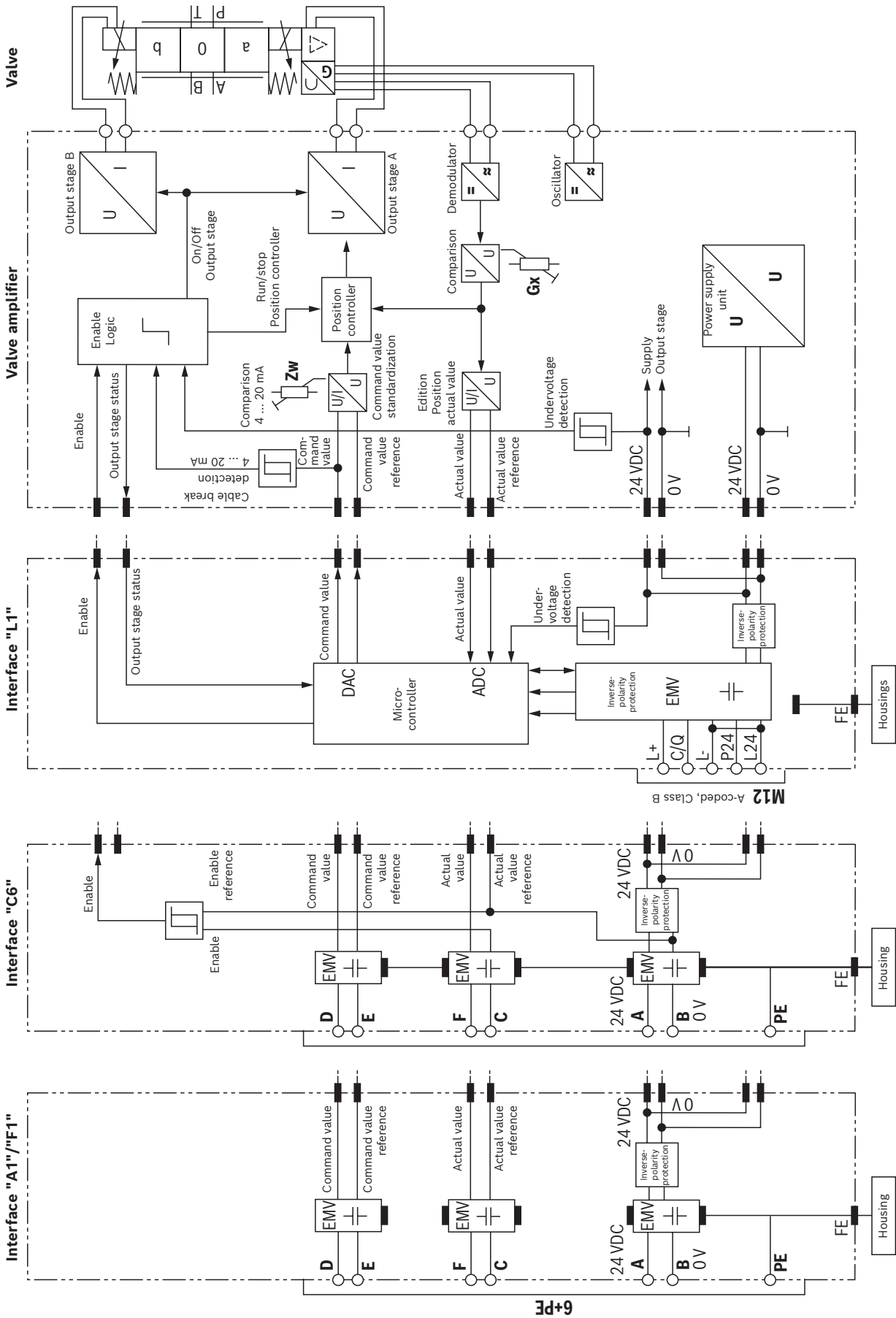
Electrical, integrated electronics (OBE) – Interface "C6"			
Supply voltage	► Nominal value	VDC	24
	► Minimum	VDC	19
	► Maximum	VDC	36
	► Maximum residual ripple	Vpp	2.5
	► Maximum power consumption	VA	40
	► Fuse protection, external	A _T	2.5 (time-lag)
Relative duty cycle time according to VDE 0580		%	S1 (continuous operation)
Functional ground and screening		See page 14 (EMC-compliant installation)	
Command value	► Input current range	mA	±10
	► Input resistance	Ω	200
Actual value (test signal)	► Output range	mA	4 ... 20
	► Maximum load	Ω	500
Enable	► Low level range	V	–3 ... 5
	► High level range	V	11 ... U_B
	► Maximum current consumption at high level	mA	7.25 ($U_B = 24$ V); 11 ($U_{B \max}$)

Technical data

(For applications outside these values, please consult us!)

Electrical, integrated electronics (OBE) – Interface "L1"		
Supply voltage	► Valve amplifiers	
	– Nominal value	VDC 24
	– Minimum	VDC 18
	– Maximum	VDC 30
	– Maximum residual ripple	Vpp 1.3
	– Maximum power consumption	VA 40
	► IO-Link interface	
	– Nominal value	VDC 24
	– Minimum	VDC 18
	– Maximum	VDC 30
	– Maximum residual ripple	Vpp 1.3
	– Maximum power consumption	VA 1.2
Relative duty cycle time according to VDE 0580		% S1 (continuous operation)
Functional ground and screening		Provide via valve block
Bit rate COM3		kBaud 230.4 (kbit/s)
Required master port class		Class B
Directive		IO-Link Interface and System Specification Version 1.1.2

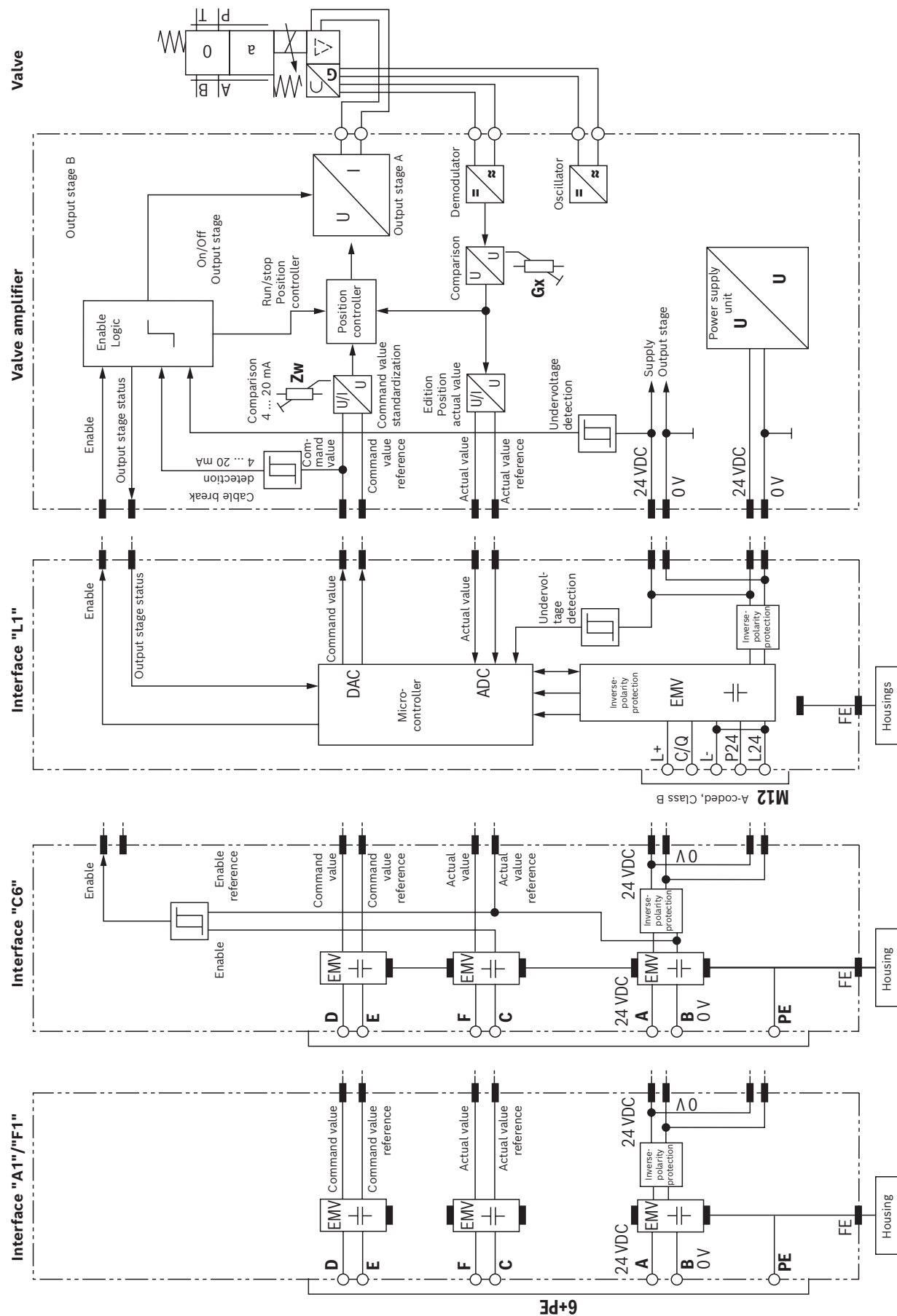
Block diagram/controller function block (4/3-way version)



Notice:

- ▶ Electrical signals provided via control electronics (e.g. actual value) must not be used for switching off safety-relevant machine functions.
- ▶ The setting of the potentiometer at the factory must not be changed.

Block diagram/controller function block (4/2-way version)

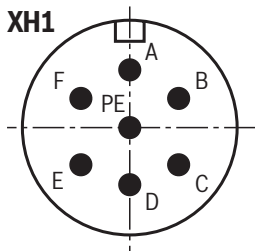


Notice:

- Electrical signals provided via control electronics (e.g. actual value) must not be used for switching off safety-relevant machine functions.
- The setting of the potentiometer at the factory must not be changed.

Electrical connections and assignment

Contact	Interface assignment		
	"A1" (6 + PE)	"F1" (6 + PE)	"C6" (6 + PE)
A	Supply voltage	Supply voltage	Supply voltage
B	GND	GND	GND, reference potential actual value/enable (Current loop I_{F-B} feedback)
C	Reference potential actual value	Reference potential actual value (Current loop I_{F-C} feedback)	Enable input
D	Command value	Command value	Command value
E	Reference potential command value	Reference potential command value (Current loop I_{D-E} feedback)	Reference potential command value (Current loop I_{D-E} feedback)
F	Actual value	Actual value	Actual value
FE	Functional ground (directly connected to the valve housing)		

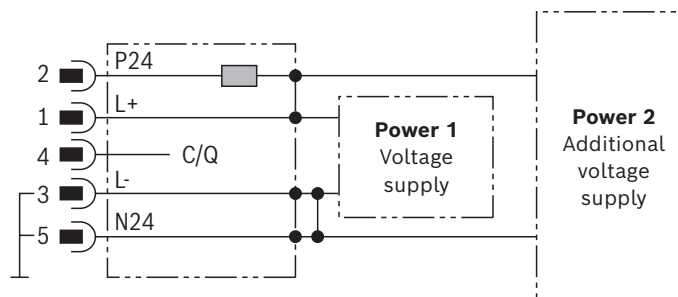
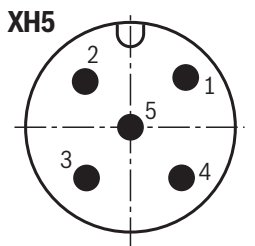


Command value	► Positive command value (0 ... 10 V or 12 ... 20 mA) at D and reference potential at E cause flow from P → A and B → T. ► Negative command value (0 ... -10 V or 12 ... 4 mA) at D and reference potential at E cause flow from P → B and A → T.
Connection cable	► Up to 20 m cable length type LiYCY 7 x 0.75 mm² ► Up to 40 m cable length type LiYCY 7 x 1.0 mm² ► EMC-compliant installation: – Apply screening to both line ends – Use metal mating connector (see page 27) ► Alternatively up to 30 m cable length admissible – Apply screening on supply side – Plastic mating connector (see page 27) can be used


Notice:

Mating connectors, separate order, see page 27 and data sheet 08006.

Connector pin assignment "L1" (M12-5, A-coded, class B)


Notice:

- M12 sensor/actuator connection line, 5-pole; M12 connector/bush, A-coded, without shield, maximum cable length 20 m (observe the voltage drop over the cable; wire cross-section at least 0.34 mm² for a cable length of up to 5 m).
- Mating connectors, separate order, see page 27 and data sheet 08006.
- For the communication and parameter description see data sheet 29400-PA

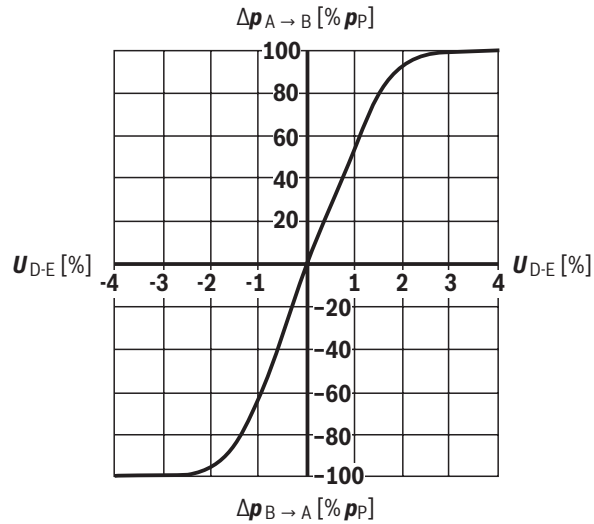
Pin	Signal	Allocation interface L1
1	L+	Voltage supply IO-Link
2	P24	Voltage supply valve electronics and power part (current consumption 3 A)
3	L-	Reference potential pin 1 ¹⁾
4	C/Q	Data line IO-Link (SDCI)
5	N24	Reference potential pin 2 ¹⁾

¹⁾ Pin 3 and 5 are linked with each other in the valve electronics. The reference potentials L- and N24 of the two supply voltages must also be linked with each other on the power supply unit side.

Characteristic curves

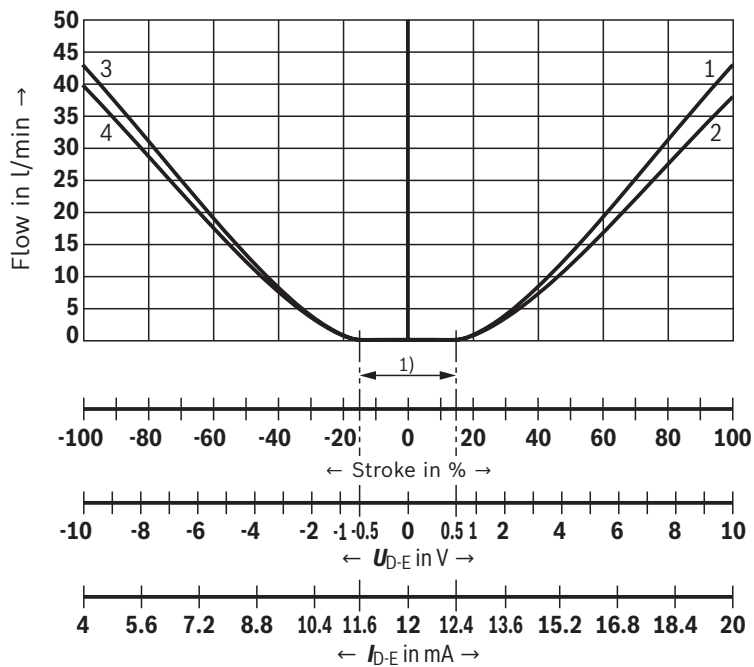
(measured with HLP46, $\vartheta_{\text{oil}} = 40 \pm 5 \text{ }^{\circ}\text{C}$)

Pressure/signal characteristic curve (symbol V)



Flow/signal function (rated flow 50 l/min with $\Delta p = 5 \text{ bar}$ /control edge)

Symbol E

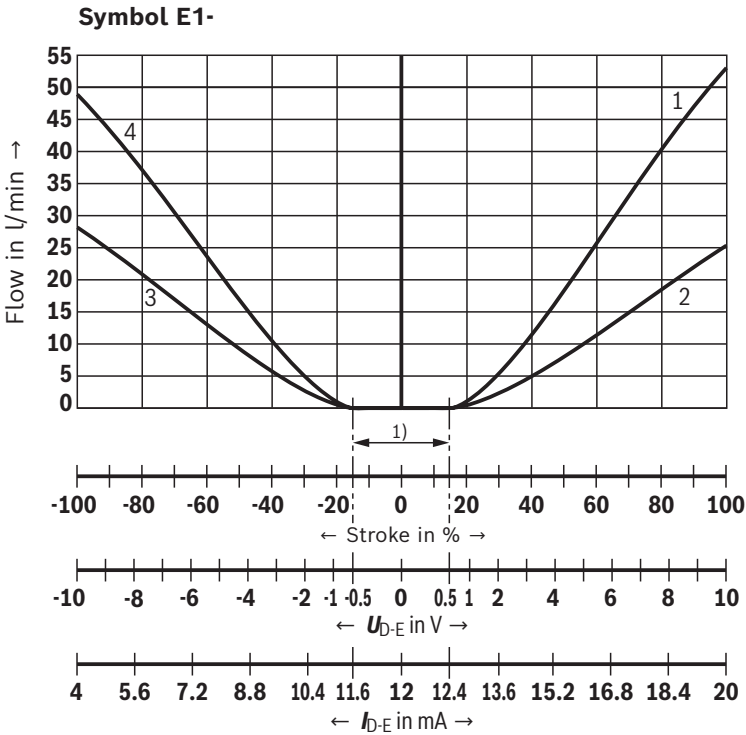


1) Step compensation

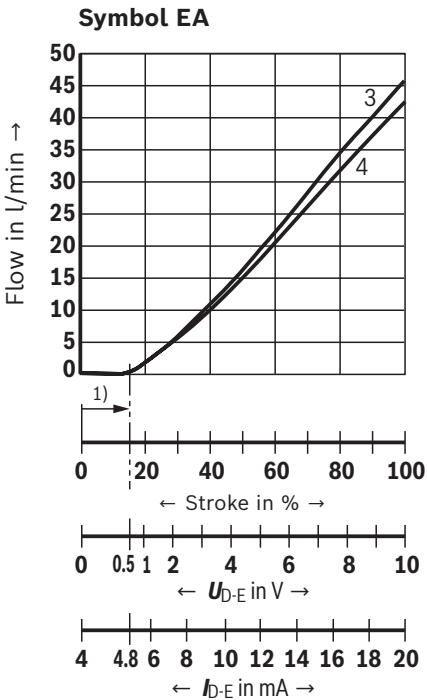
- 1 P-A
- 2 B-T
- 3 P-B
- 4 A-T

Characteristic curves
(measured with HLP46, $\vartheta_{oil} = 40 \pm 5 \text{ }^{\circ}\text{C}$)

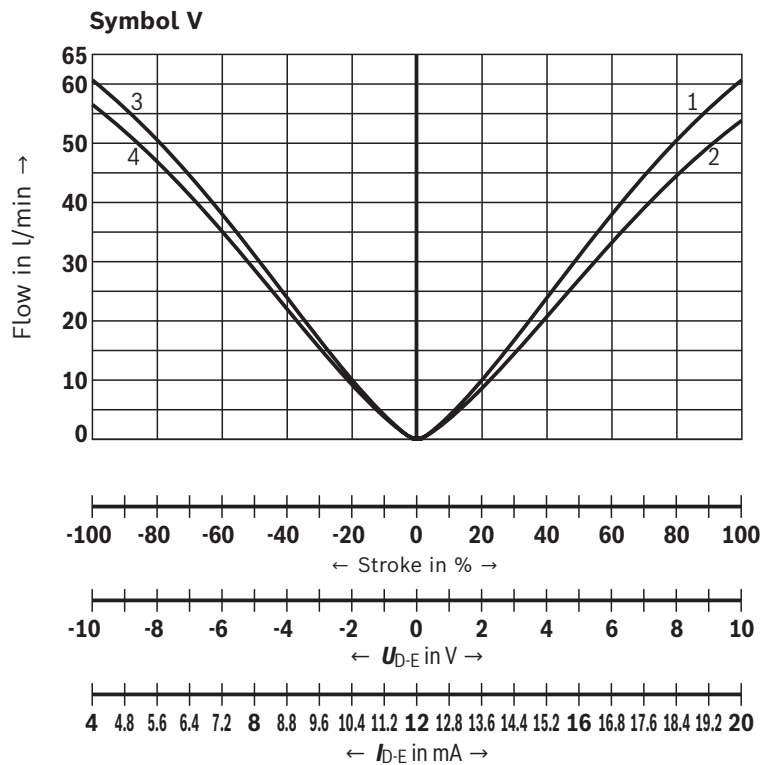
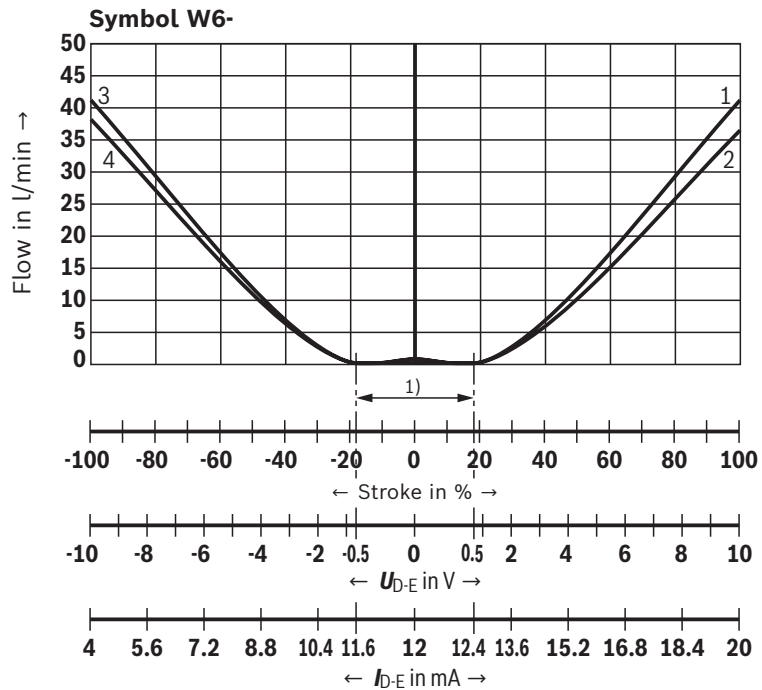
Flow/signal function (rated flow 50 l/min with $\Delta p = 5 \text{ bar}$ /control edge)



- 1) Step compensation
- 1 P-A
 - 2 B-T
 - 3 P-B
 - 4 A-T

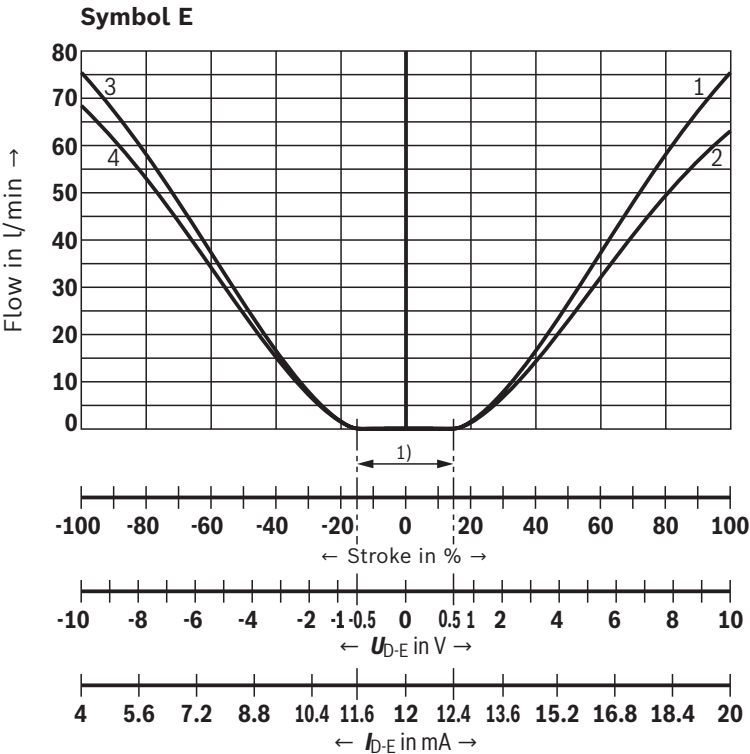


- 1) Step compensation
- 3 P-B
 - 4 A-T

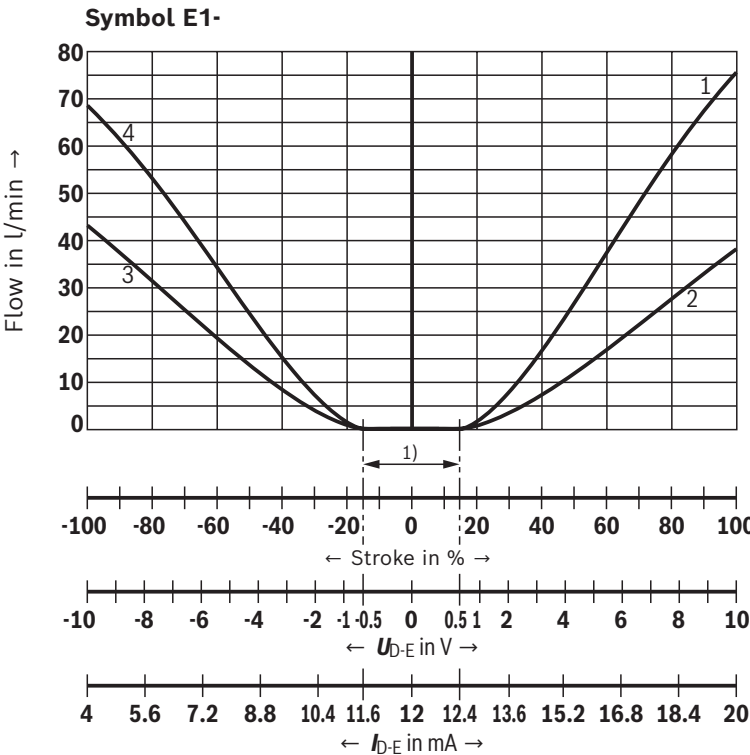
Characteristic curves(measured with HLP46, $\vartheta_{\text{oil}} = 40 \pm 5 \text{ }^{\circ}\text{C}$)**Flow/signal function** (rated flow 50 l/min with $\Delta p = 5 \text{ bar/control edge}$)

Characteristic curves
(measured with HLP46, $\vartheta_{oil} = 40 \pm 5 \text{ }^{\circ}\text{C}$)

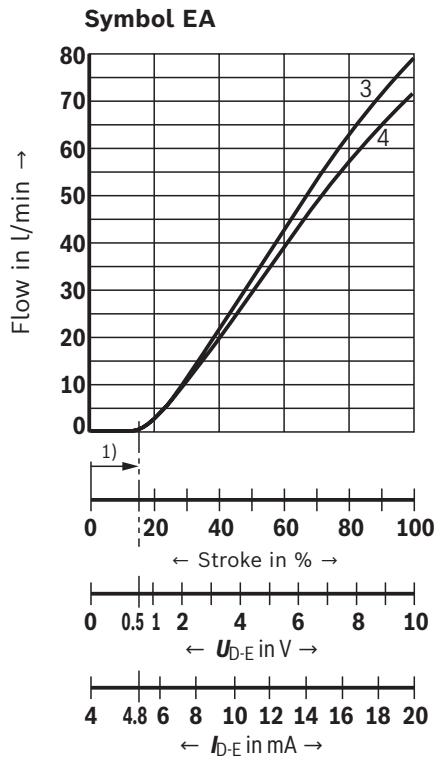
Flow/signal function (rated flow 80 l/min with $\Delta p = 5 \text{ bar/control edge}$)



- 1) Step compensation
- 1 P-A
 - 2 B-T
 - 3 P-B
 - 4 A-T



- 1) Step compensation
- 1 P-A
 - 2 B-T
 - 3 P-B
 - 4 A-T

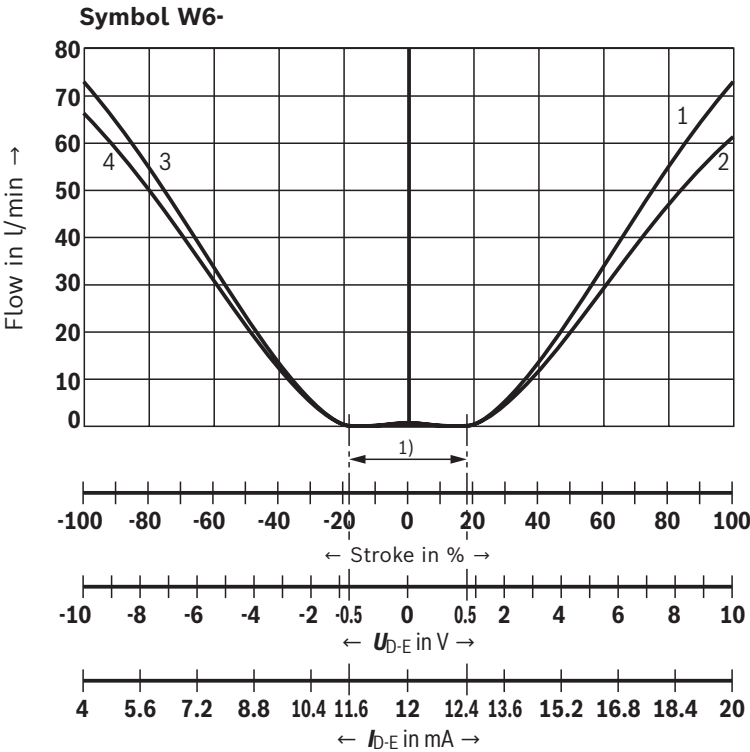
Characteristic curves(measured with HLP46, $\vartheta_{\text{oil}} = 40 \pm 5 \text{ }^{\circ}\text{C}$)**Flow/signal function** (rated flow 80 l/min with $\Delta p = 5 \text{ bar}$ /control edge)

1) Step compensation

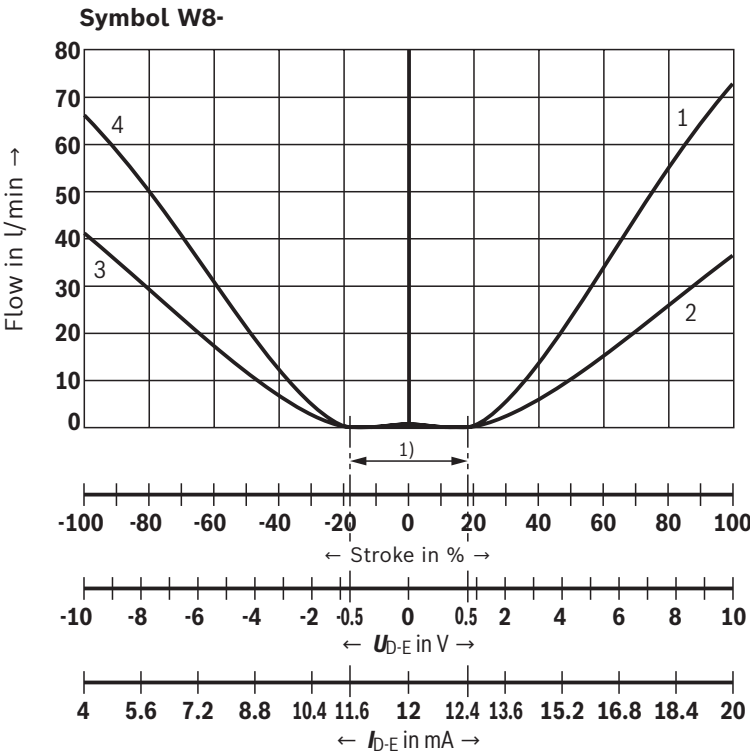
3 P-B**4** A-T

Characteristic curves
(measured with HLP46, $\vartheta_{oil} = 40 \pm 5 \text{ }^{\circ}\text{C}$)

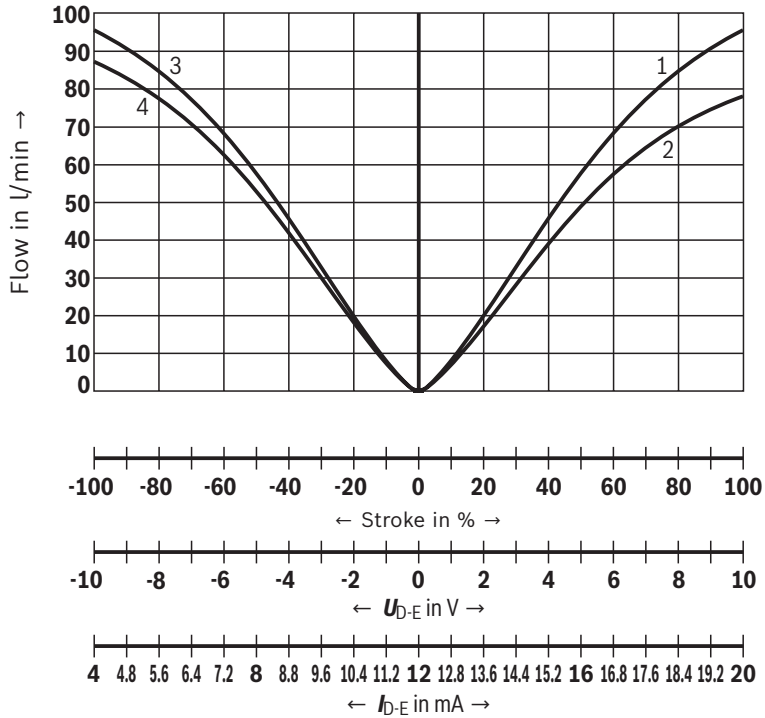
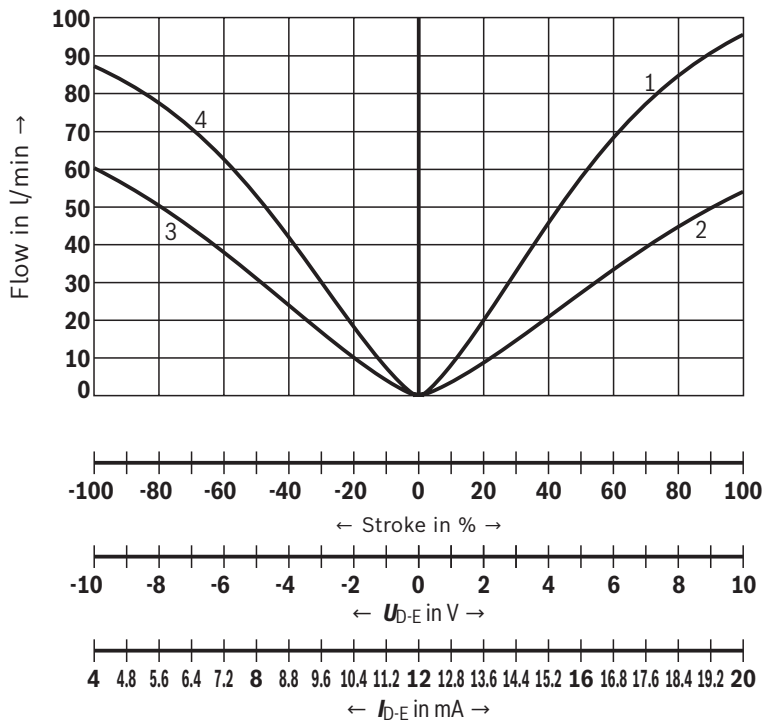
Flow/signal function (rated flow 80 l/min with $\Delta p = 5 \text{ bar/control edge}$)



- 1) Step compensation
- 1 P-A
 - 2 B-T
 - 3 P-B
 - 4 A-T

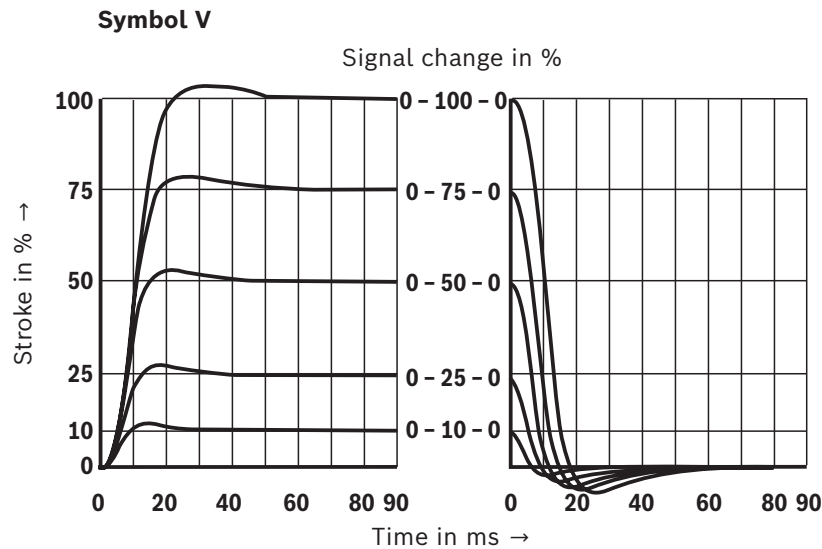


- 1) Step compensation
- 1 P-A
 - 2 B-T
 - 3 P-B
 - 4 A-T

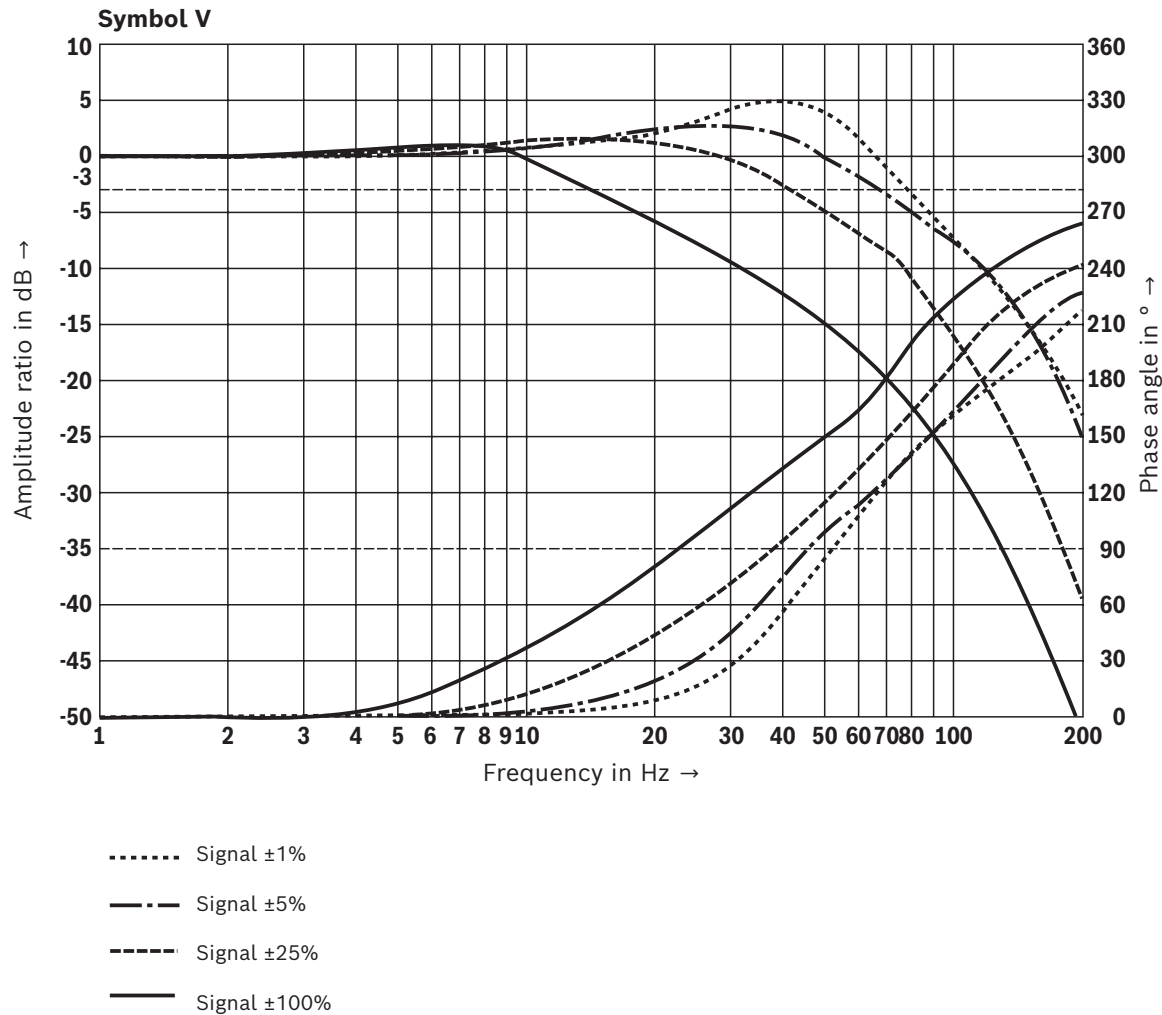
Characteristic curves(measured with HLP46, $\vartheta_{oil} = 40 \pm 5 \text{ } ^\circ\text{C}$)**Flow/signal function** (rated flow 80 l/min with $\Delta p = 5 \text{ bar/control edge}$)**Symbol V****Symbol V1-**

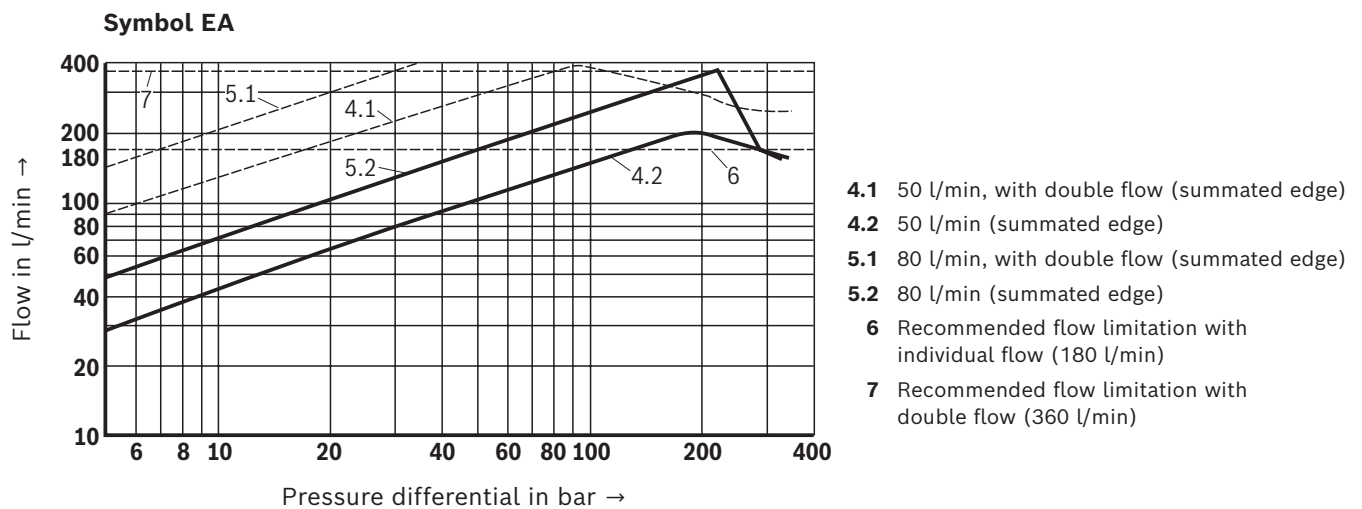
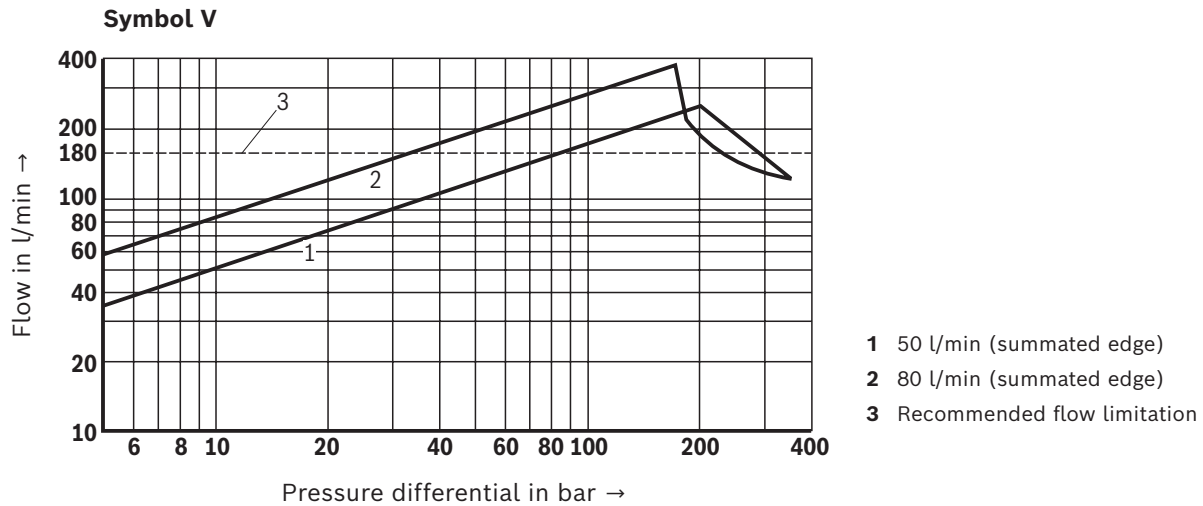
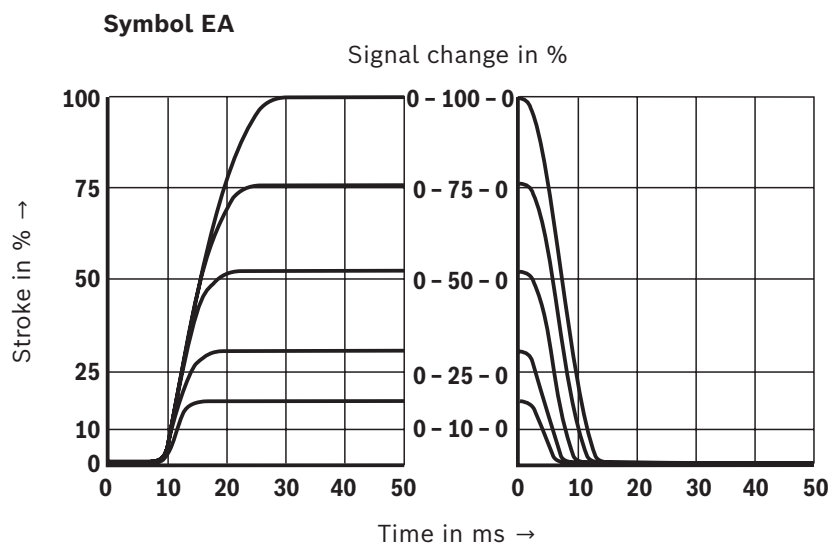
Characteristic curves
(measured with HLP46, $\vartheta_{oil} = 40 \pm 5 \text{ }^{\circ}\text{C}$)

Transition function with stepped electric input signals (4/3-way version)

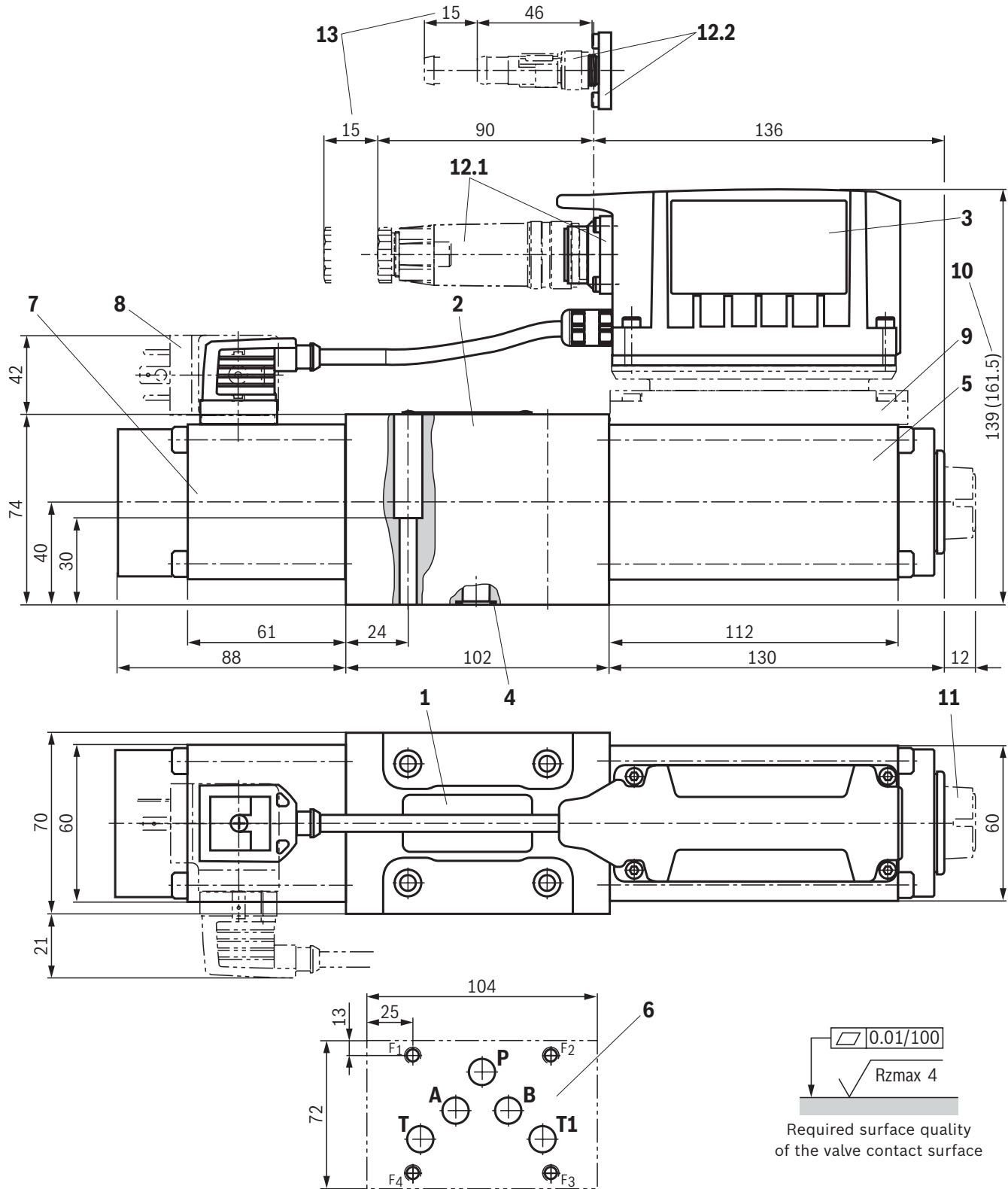


Frequency response



Characteristic curves(measured with HLP46, $\vartheta_{oil} = 40 \pm 5 \text{ }^{\circ}\text{C}$)**Flow/load function with maximum valve opening** (tolerance $\pm 10\%$) (4/3-way version)**Transition function with stepped electric input signals** (4/2-way version)

Dimensions (4/3-way version)
(dimensions in mm)



Notice:

- ▶ The dimensions are nominal dimensions which are subject to tolerances.
- ▶ Mating connectors, separate order, see page 27 and data sheet 08006.

For item explanations, valve mounting screws and subplates, see page 26.

Dimensions

- 1 Name plate
- 2 Valve housing
- 3 Integrated electronics (OBE)
- 4 Identical seal rings for ports A, B, P, T, T1
- 5 Control solenoid with position transducer
- 6 Machined valve contact surface, porting pattern according to ISO 4401-05-04-0-05
- 7 Stroke solenoid
- 8 ISA adapter, separate order, see page 27
- 9 Damping plate "D"
- 10 Dimension in () for version with damping plate "D"
- 11 Electronics protection membrane "-967"
- 12.1 Mating connectors for version "A1", "F1" and "C6", separate order, see page 27 and data sheet 08006.
- 12.2 Mating connectors for version "L1", separate order, see page 27 and data sheet 08006.
- 13 Space required for removing the mating connector

Valve mounting screws (separate order)

Size	Quantity	Hexagon socket head cap screws
10	4	ISO 4762 - M6 x 40 - 10.9-CM-Fe-ZnNi-5-Cn-T0-H-B (Friction coefficient $\mu_{\text{total}} = 0.09 \dots 0.14$) Tightening torque $M_A = 12.5 \text{ Nm} \pm 10\%$
	or	
	4	ISO 4762 - M6 x 40 - 10.9 Tightening torque $M_A = 15.5 \text{ Nm} \pm 10\%$
	or	
	4	ASME B18.3 - 1/4-20 UNC x 1 3/4" - ASTM-A574 Tightening torque $M_A = 15 \text{ Nm}$ [11 ft-lbs] $\pm 10\%$



Notice:

The tightening torque of the hexagon socket head cap screws refers to the maximum operating pressure.

Subplates (separate order) with porting pattern according to ISO 4401-05-04-0-05 see data sheet 45100.

Accessories (separate order)

Valves with integrated electronics

Mating connectors 6-pole + PE	Design	Version
For the connection of valves with integrated electronics, round connector 6+PE, line cross-section 0.5 ... 1.5 mm ²	Straight	Metal
	Straight	Plastic
	Angled	Plastic

Cable sets 6-pole + PE	Length in m
For the connection of valves with integrated electronics, round connector 6+PE, straight connector, shielded, potted-in mating connector, line cross-section 0.75 mm ²	3.0
	5.0
	10.0
	20.0

Valves with integrated electronics and IO-Link interface

Cable sets for IO-Link	Length in m
For the connection of valves with IO-Link interface, M12-5, A-coded, unshielded, line cross-section 5 x 0.34 mm ²	1.5
	3.0
	5.0

Test and service devices

Service case with test device for proportional servo valves with integrated electronics (OBE)	
ISA adapter	ISA adapter for external shut-off of the second solenoid (tightening torque $M_A = 0.5^{+0.1}$ Nm)

Project planning information

- The use of the valves with IO-Link as a shut-off element up to category 3, PL d according to EN 13849-1 is possible from component series 31. For additional application notes regarding safe "shut-off", see operating instructions 29118-B.
- For component series 30, the valve cannot be used for "safe shut-off".

